# JIARUN WEI

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# EDUCATION

09/2020 - 05/2022**Carnegie Mellon University** Master of Science - Mechanical Engineering Courses: Deep Learning, Computer Vision, Java for Application Programmer, Machine Learning

# University of California. Berkelev

Exchange Study - Concurrent Enrollment Courses: Feedback Control of Legged Robots, Introduction to Control of UAV, Model Predictive Control

# Dalian University of Technology

Bachelor of Engineering - Mechanical Engineering

### Courses: C Programming, Fundamentals of Controls, Digital Circuits

### **EXPERIENCE**

### Division of Autonomous System, Autox Inc | Company Website Software Engineer

- Working on the algorithm and evaluation system for autonomous reroute under complex scenarios in C++
- Built an interactive system to automatically setup and monitor autonomous driving vehicles by Shell Script
- Designed a **HTTP** server to improve the autonomous vehicle set up, communication efficiency and security

# Safe AI Lab, CMU | Demo

Research Assistant

- Developed an autonomous delivery robot with Visual and Lidar perception by C++ and Python in Linux
- Designed an automatic Camera-Lidar calibration algorithm using key-point correspondence approach by C++
- Achieved stable localization by FAST-LIO algorithm with Solid State Lidar and Stereo Camera IMU in ROS

### PROJECTS

#### Monocular Depth Prediction Using Self-supervised Learning | Project repo 04/2022 - Present

- Built and trained a 2D image depth prediction neural network in **PyTorch** based on self-supervised learning
- Improved the prediction stability by adjusting Graph Adjacency Matrices in Graph Convolutional Network
- Implemented an automatic data selection and image color augmentation algorithm for **KITTI** dataset

# Webiste Development for ICRA Competition | Website

- Developed a deliverable website for SeasonDepth Challenge Competition using HTML, recorded by ICRA
- Fulfilled the front end interfaces of registration, login and ranking page by customized **CSS** and **Bootstrap**
- Deployed the website on RDS server and associated it with a domain name to evaluate the participants' models

# **Zombies-Infection Game** | Project repo

- Implemented a third person shooting game based on Object Oriented Programming by C++ and OpenGL
- Constructed super classes of virtual props with extensible methods as interfaces in convenience of inheritance
- Optimized the texture loading time during weapon switching based on a novel pointer management algorithm

# Collision Check for Robot Arms | Project repo

- Designed a safety region generation approach for robot arm collision check by **Python** and **MATLAB**
- Implemented a self-designed algorithm to solve the geometric parameters of the safety region based on SVD
- Developed a CAD software plugin to calculate and visualize the safety region of 3D objects in arbitrary shape

# Emoji Prediction for Twitter Texts | Project repo

- Constructed a deep learning pipeline for emoji prediction on twitter texts based on CNN and LSTM by Keras
- Applied the Word2vec and GloVe embedding algorithm to data prepossessing and feature encoding of texts
- Conducted data cleaning and word parsing based on statistical method to get rid of the irrelevant information

# SKILLS

Languages:	C/C++, Python, Java, JavaScript, Shell Script, HTML, MATLAB
Tool-kits:	PyTorch, MMCV, Wandb, Tensorboard, Numpy, Scipy, Git, Bootstrap, Latex
Environment:	Linux, GNU GRUB, SSH, Vim, ROS, Conda, Docker, CARLA

10/2021 - 12/2021

11/2020 - 12/2020

10/2020 - 12/2020

01/2022 - 03/2022

09/2016 - 06/2020

01/2019 - 12/2019

Dalian, CN

Pittsburgh, PA

Berkeley, CA

# 06/2022 - Present

San Jose, CA

09/2021 - 05/2022

### Pittsburgh. PA